

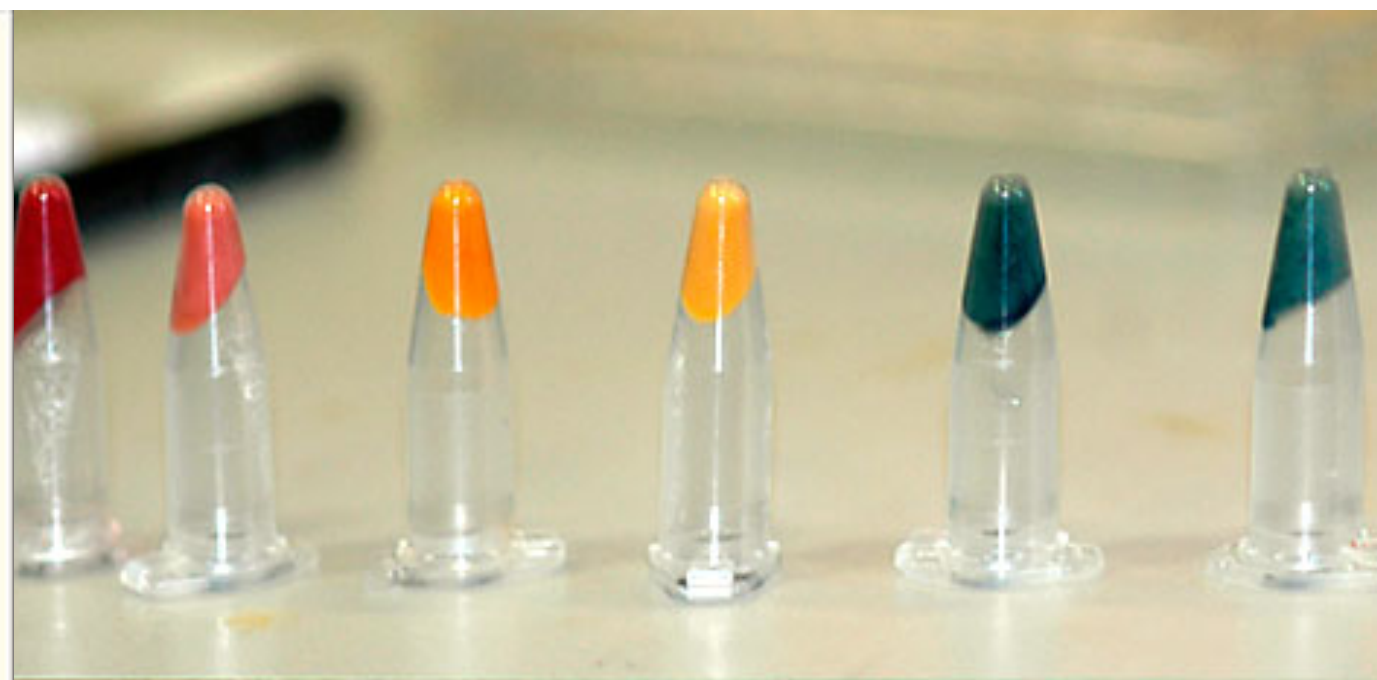
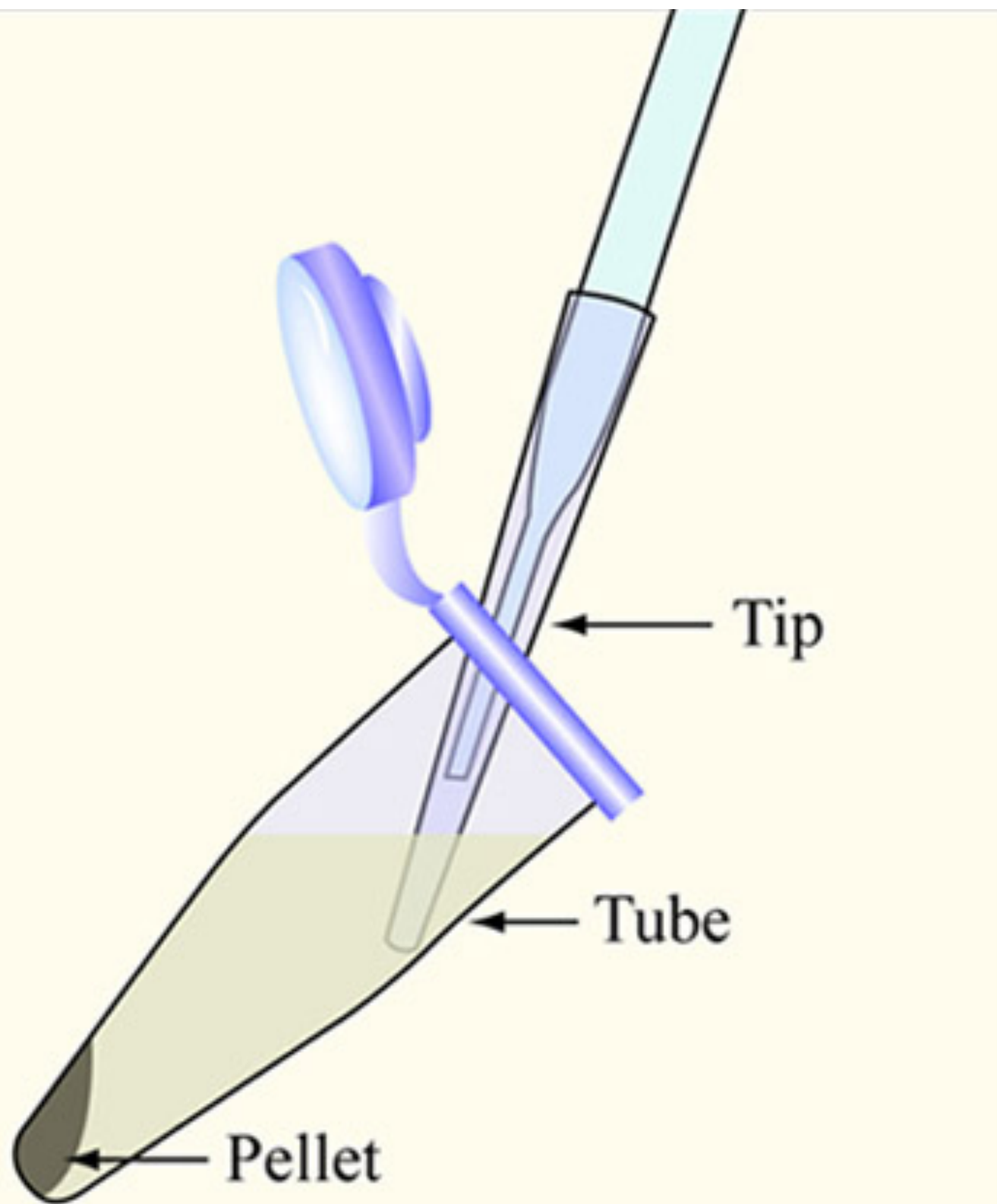


**waag**  
**wetlab amsterdam**

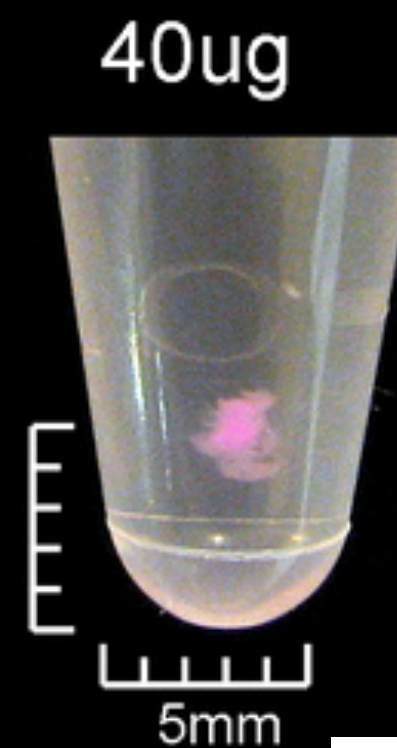
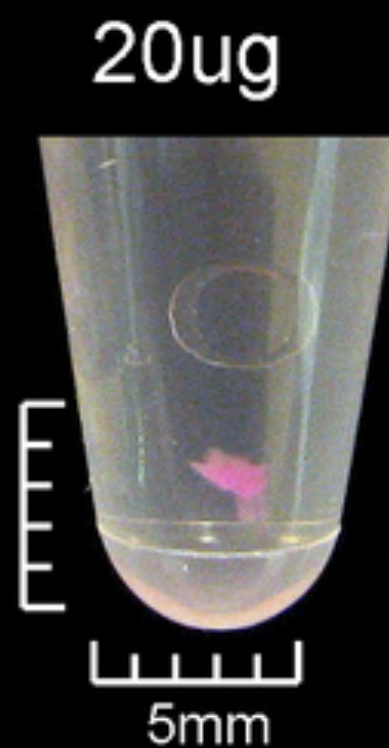
**BioHack Academy**  
**Centrifuge Design**



# Centrifugation



Cambridge iGEM 2009





# Industry standards



Magnus Manske - CC-BY 1.0





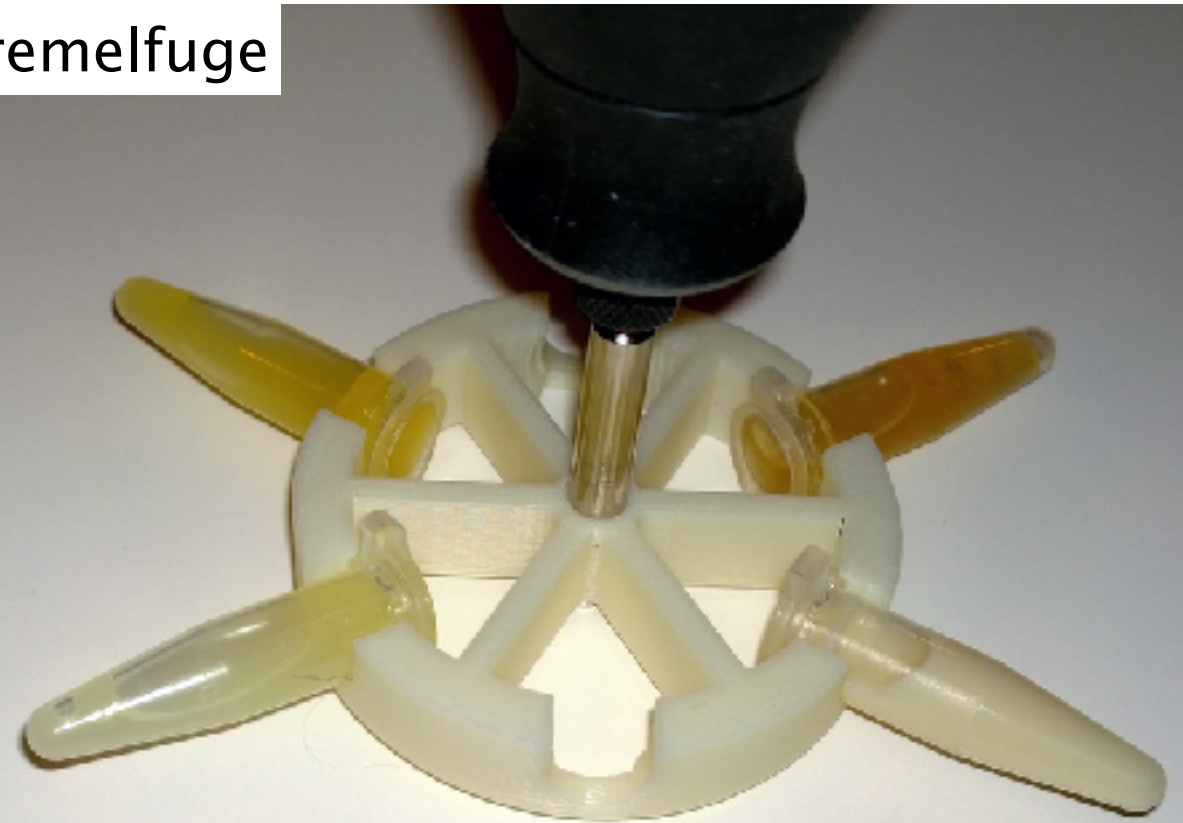


# Centrifuge hacks

GoGoFuge



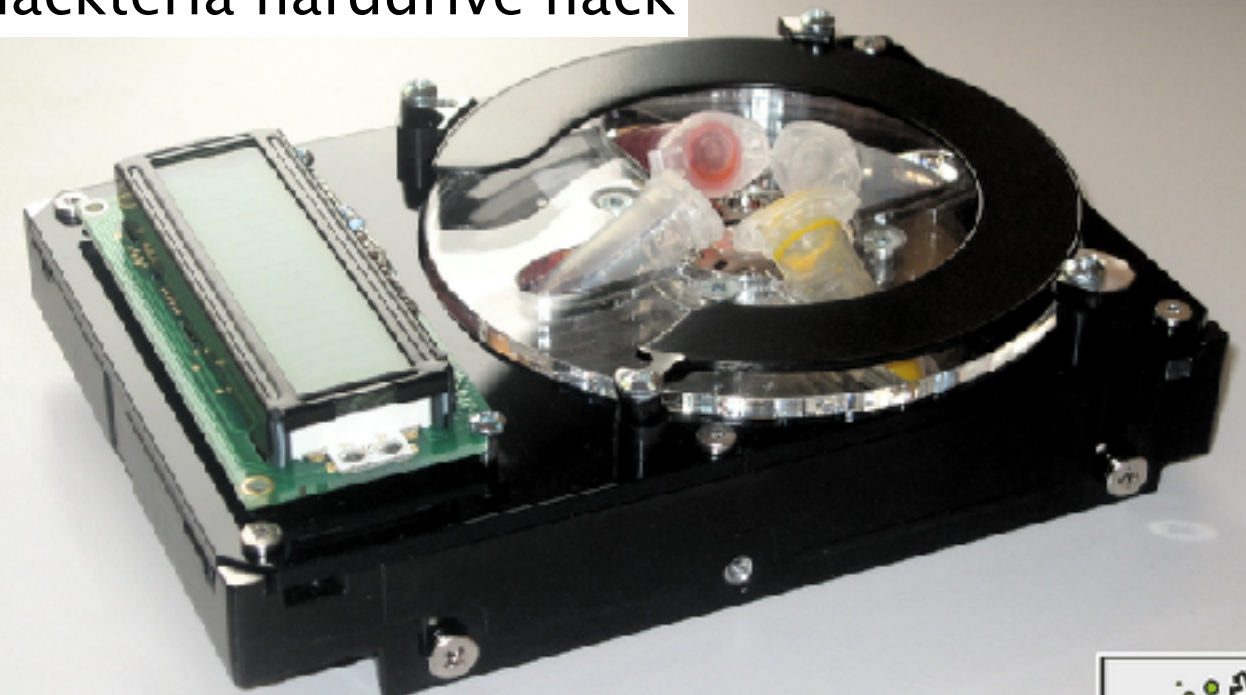
Dremelfuge



OpenFuge



Hackteria harddrive hack







# Design constraints







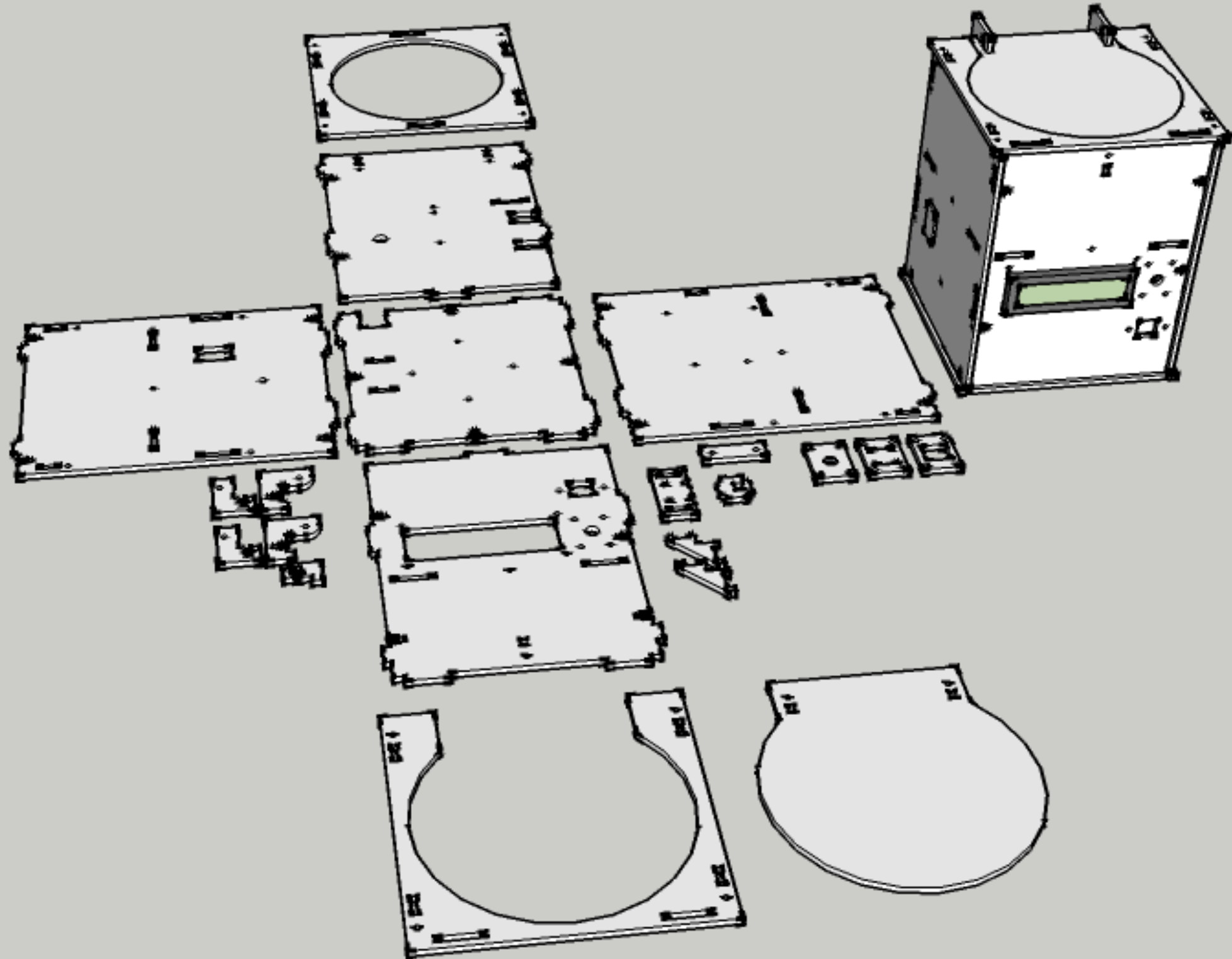
# Notice

- NEVER test your centrifuge with a rotor attached



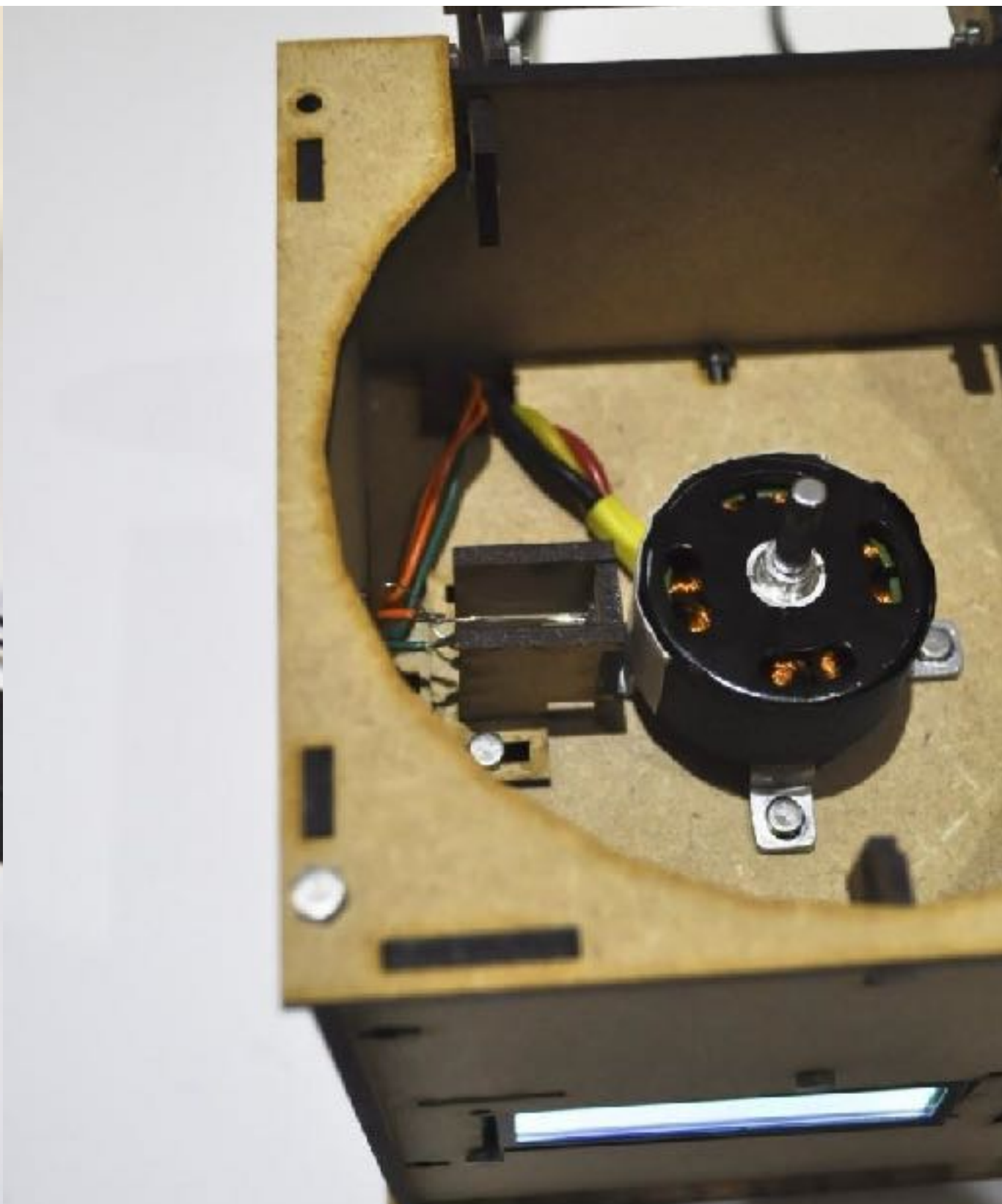
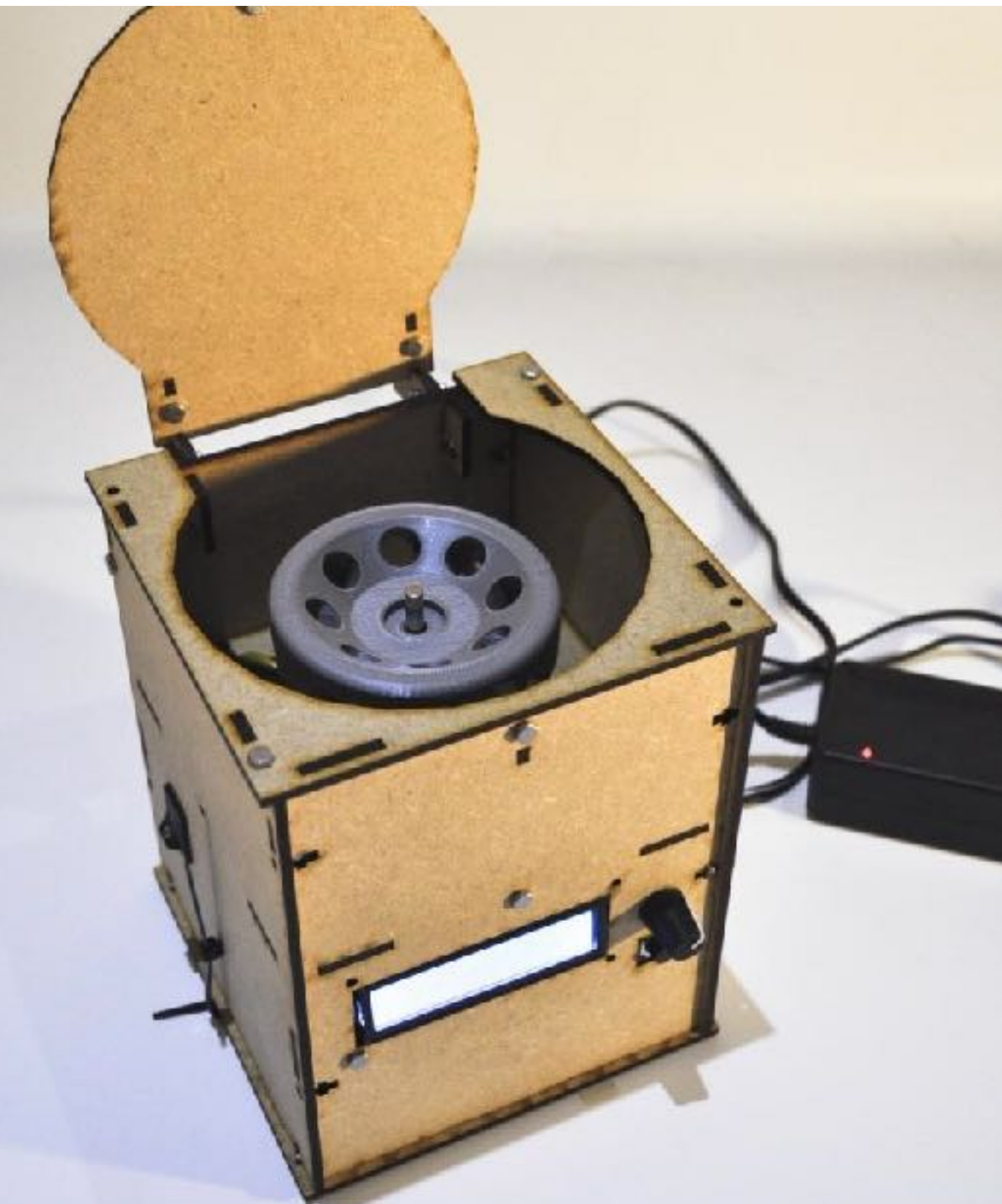


# BioHack Academy design





# Some pictures







# Bill of Materials

No	Amount	Description	Supplier NL	Cost
1	1	DC Brushless motor 800 RPM/V & Electronic Speed Controller	<a href="#">HobbyKing</a>	15.22
2	1	3.5mm connector	<a href="#">HobbyKing</a>	3.14
3	1	Rotary encoder	<a href="#">Farnell</a> , <a href="#">iPrototype</a> , <a href="#">EEO</a>	0.42
4	1	Knob	<a href="#">Farnell</a>	0.23
5	1	Power switch	<a href="#">Farnell</a> , <a href="#">iPrototype</a>	0.71
6	1	DC power jack	<a href="#">Farnell</a> , <a href="#">EEO</a>	0.85
7	1	12V 5A Power supply	<a href="#">Farnell</a> , <a href="#">EEO</a>	38.13
8	1	Push button	<a href="#">Farnell</a> , <a href="#">iPrototype</a> , <a href="#">Sparkfun</a>	0.47
9	1	10K resistor	<a href="#">Farnell</a> , <a href="#">EEO</a>	0.03
10	4	Rubber feet	<a href="#">Conrad</a>	0.08
11	1	Infrared sensor	<a href="#">Farnell</a>	1.70
12	1	6.8 KOhm resistor	<a href="#">Farnell</a>	0.02
13	1	220 Ohm resistor	<a href="#">Farnell</a>	0.02
16	1	I2C LCD display	<a href="#">iPrototype</a> , <a href="#">Hackerstore</a>	8.95
17	2	10K resistor	<a href="#">Farnell</a> , <a href="#">EEO</a>	0.6
18	2	10nF capacitor	<a href="#">Farnell</a> , <a href="#">iPrototype</a> , <a href="#">EEO</a>	0.14
19	2	100nF capacitor	<a href="#">Farnell</a> , <a href="#">EEO</a>	0.14
20	1	Breadboard	<a href="#">Farnell</a> , <a href="#">iPrototype</a>	2.56



# Motor

- Brushless
  - 810 KV
  - $\text{RPM} / \text{V} = 810$
  - 12V, so 9720 RPM
- ESC
  - power limit
  - voltage regulator

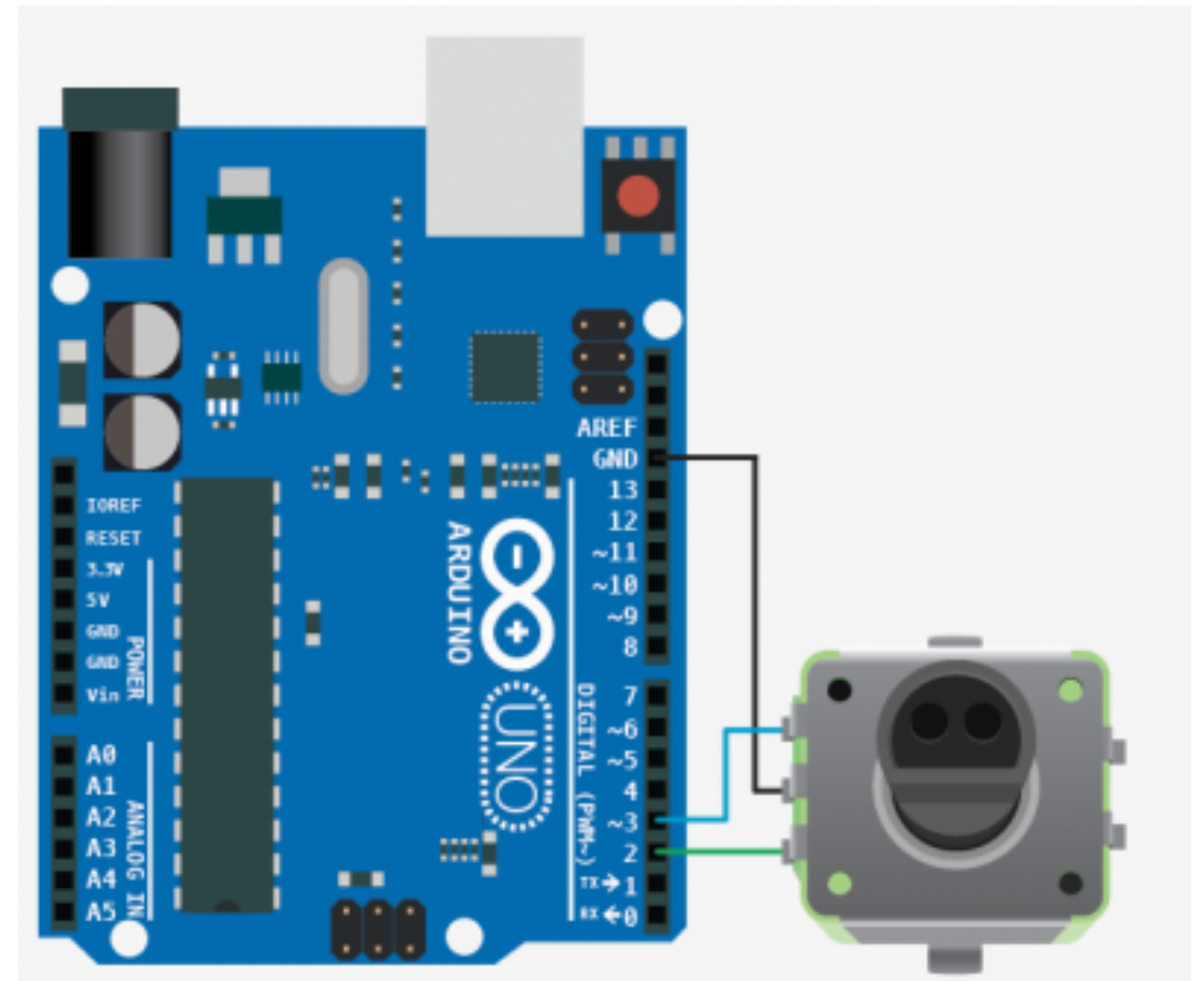






# 24 steps rotary encoder

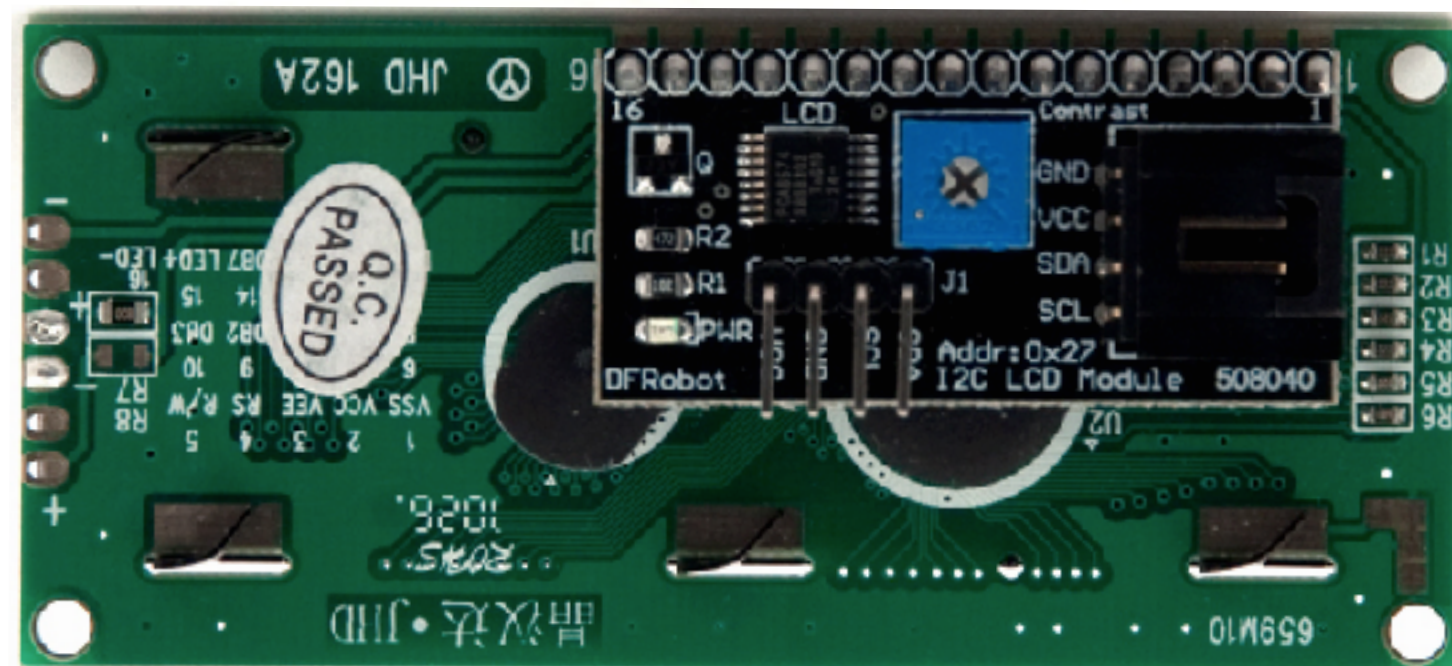
- Rotates infinitely
- 3 pins:
  - GND
  - State1
  - State2
    - 2 bits:
      - 00
      - 01
      - 11
      - 10
- Interrupt pins
  - `attachInterrupt()`
- Demo code in Syllabus





# I2C Display

- Arduino I2C ports
  - SCL -> A5
  - SDA -> A4
- Libraries
  - Wire
  - LiquidCrystal\_I2C
- Demo code in Syllabus







# Heavy weight

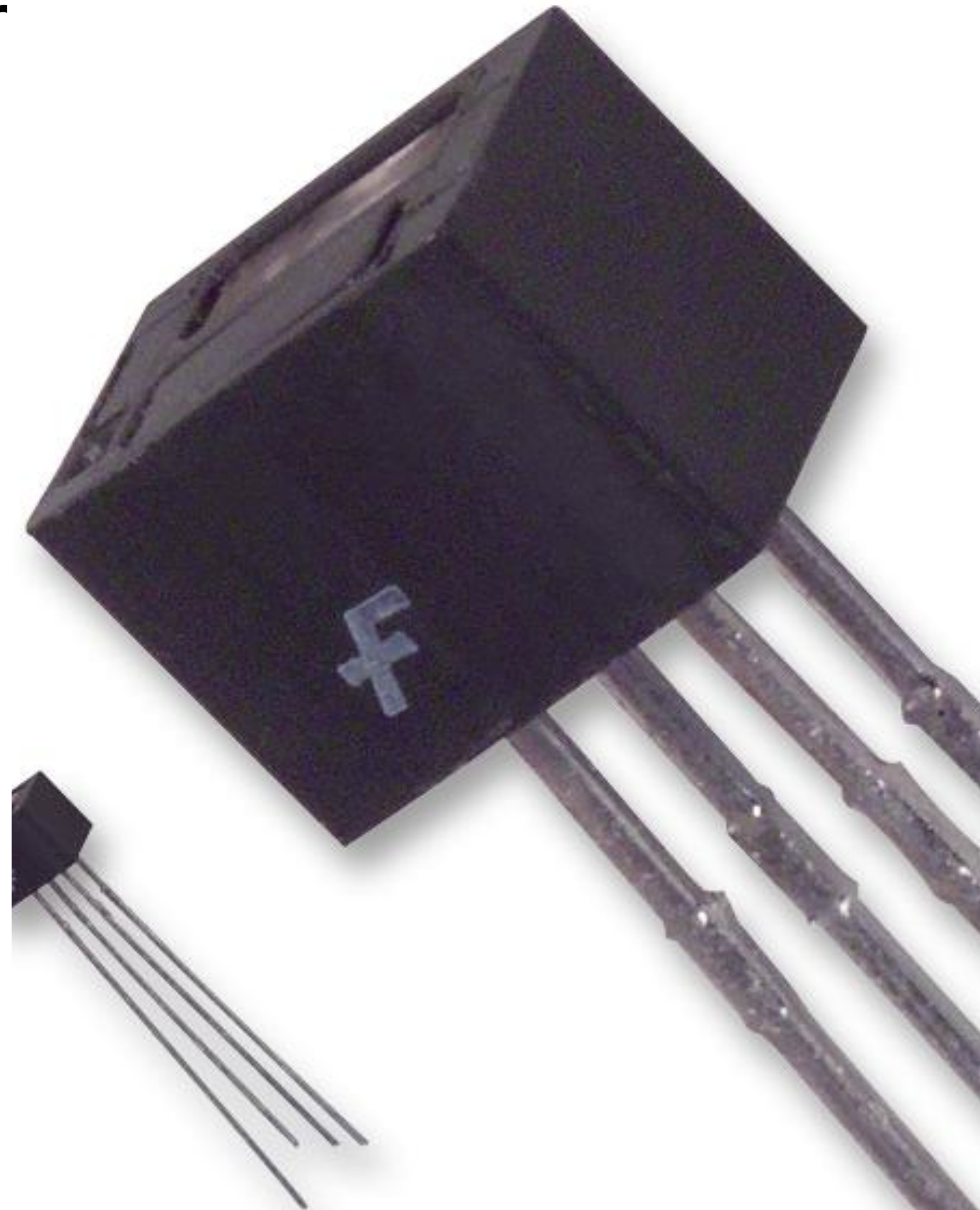
- Stabilising the machine





# Infrared sensor

- Emitter
- Detector
  
- `pulseIn()` function
  - <http://arduino.cc/en/Reference/pulseIn>







# Roller coaster

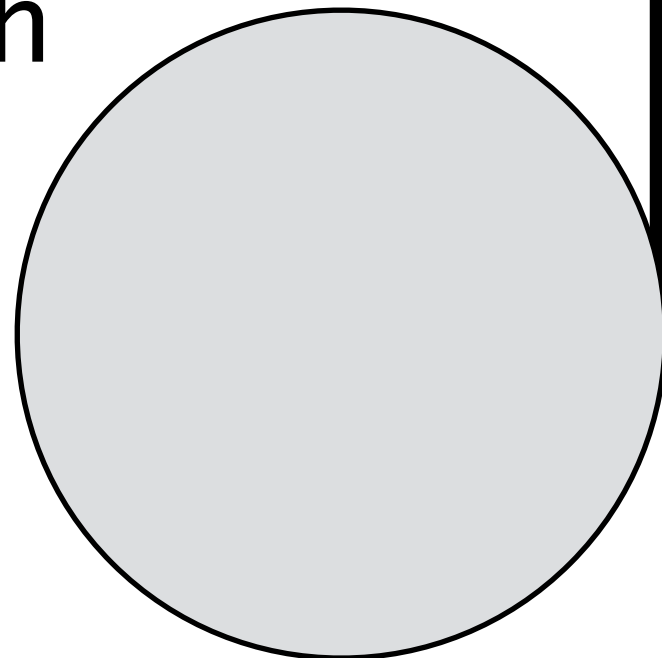






# Centrifugal force

Circular path



Inertial path





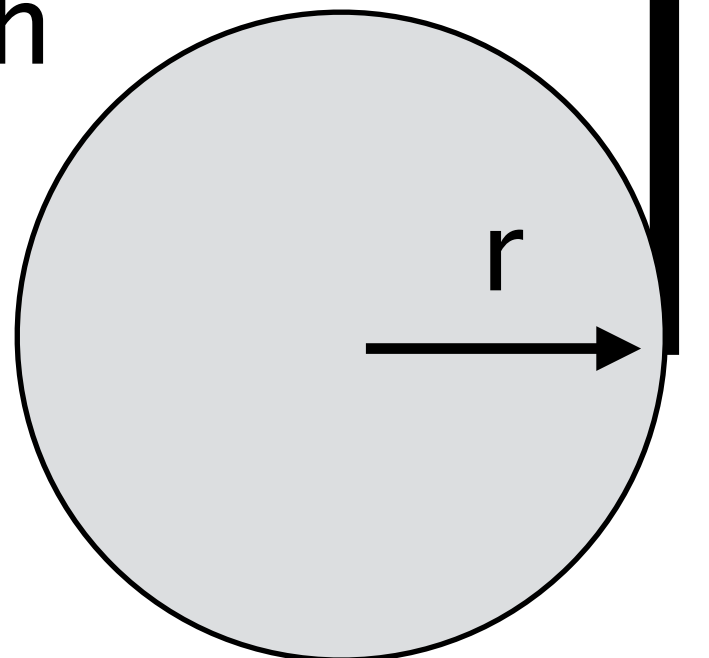


# Centrifugal force

Inertial path

$$G \text{ force} = \left(\frac{RPM}{1.000}\right)^2 \times 1.118 \times r$$

Circular path

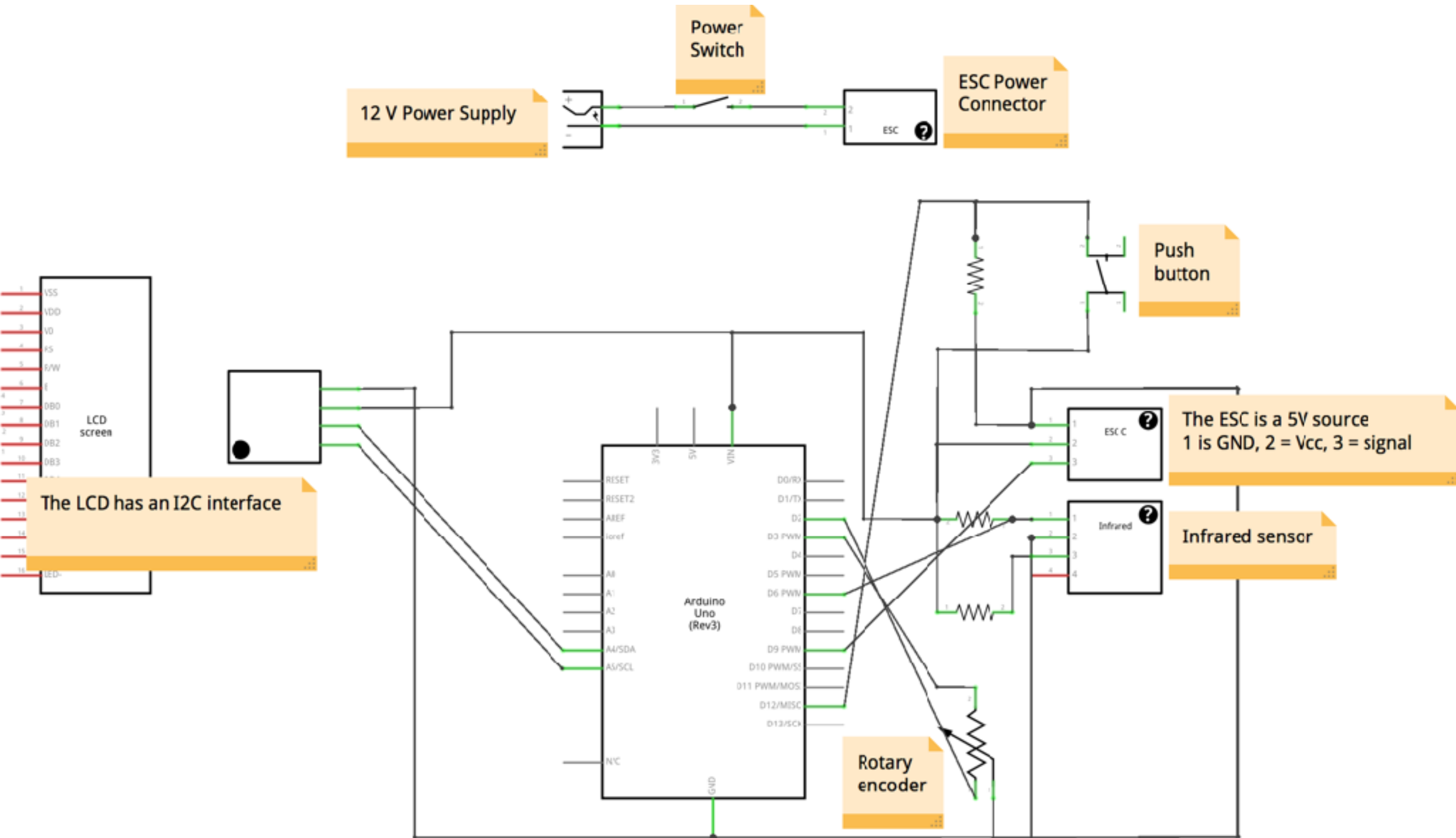








# Circuit scheme





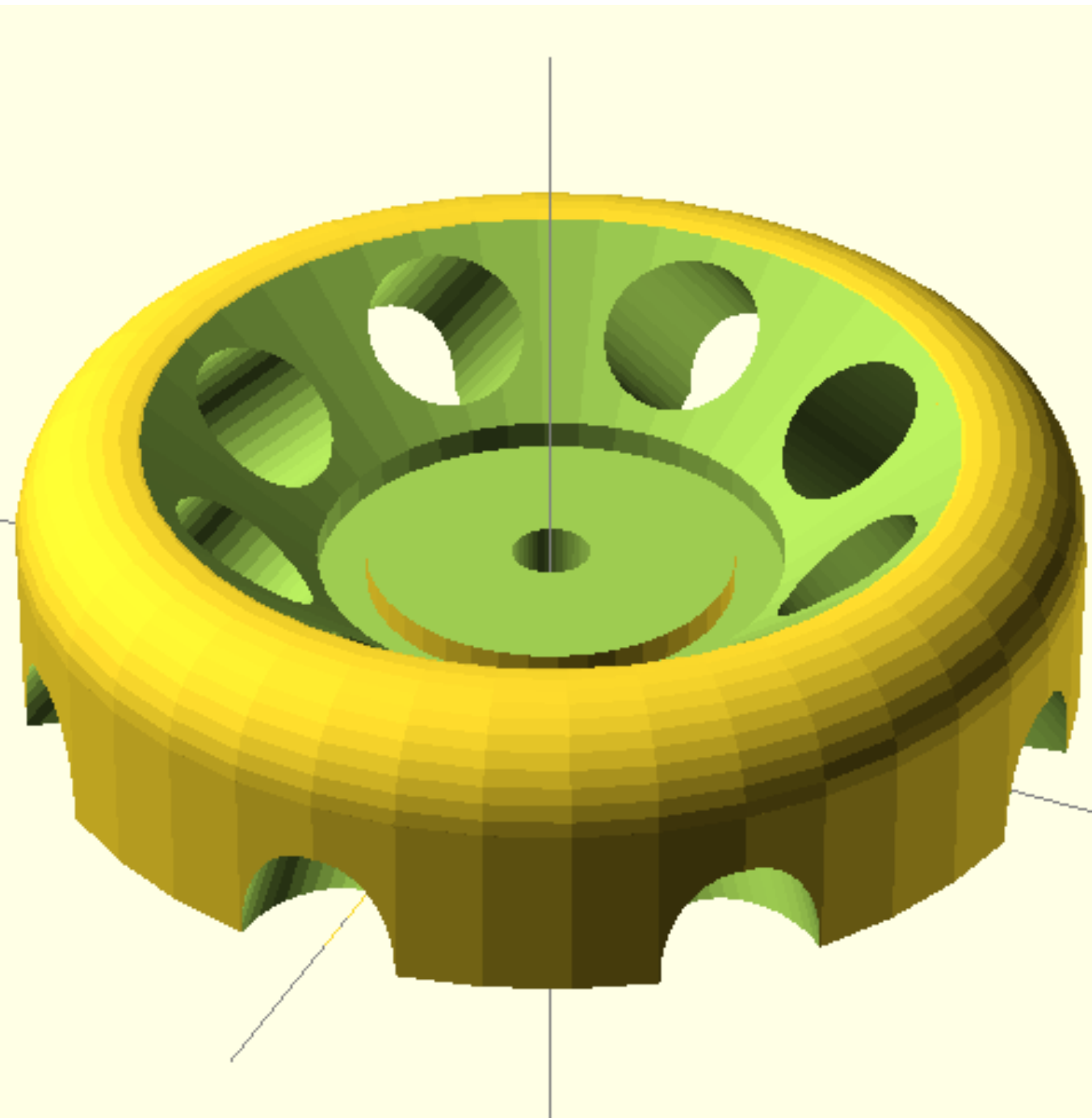
# Code tutorials

- Rotary encoder
  - <http://bildr.org/2012/08/rotary-encoder-arduino/>
- I2C LCD
  - <http://playground.arduino.cc/Code/LCDDi2c>
- Infrared sensor
  - <http://bildr.org/2011/03/various-proximity-sensors-arduino/>
- Arduino + Electronic Speed Controller
  - <http://www.instructables.com/id/ESC-Programming-on-Arduino-Hobbyking-ESC/>





# Rotor



**NEVER test your centrifuge with a rotor attached**

```
OpenSCAD - 8 Place Rotor

$fn=40; // resolution of the arcs

axis_radius = 0.275; // radius of the motor shaft

tube_radius = 0.575; // inner radius of the tube holders
tube_angle = 45; // angle in the rotor
tube_pos = 4.75; // position of tube holders

scale([10,10,10]) { // cm to mm scaling

difference() { // subtract tube holders from outer ring

    difference() { // subtract inner groove

        difference() { // subtract cone from main disk

            union() {

                cylinder (h = 1.25, r=3.75); // main disk part 1
                cylinder (h = 1.9, r=3.25); // main disk part 2

                // smoothen edge torus
                translate([0,0,1.25])
                rotate_extrude(convexity = 10)
                translate([3, 0, 0])
                circle(r = 0.75);

            }

            translate([0,0,1]) // raise cone from bottom
            cylinder (h = 1.1, r1 = 1.65, r2 = 3, center = false); // co

            translate([0,0,-0.1])
            cylinder (h = 1.2, r=axis_radius); // axis

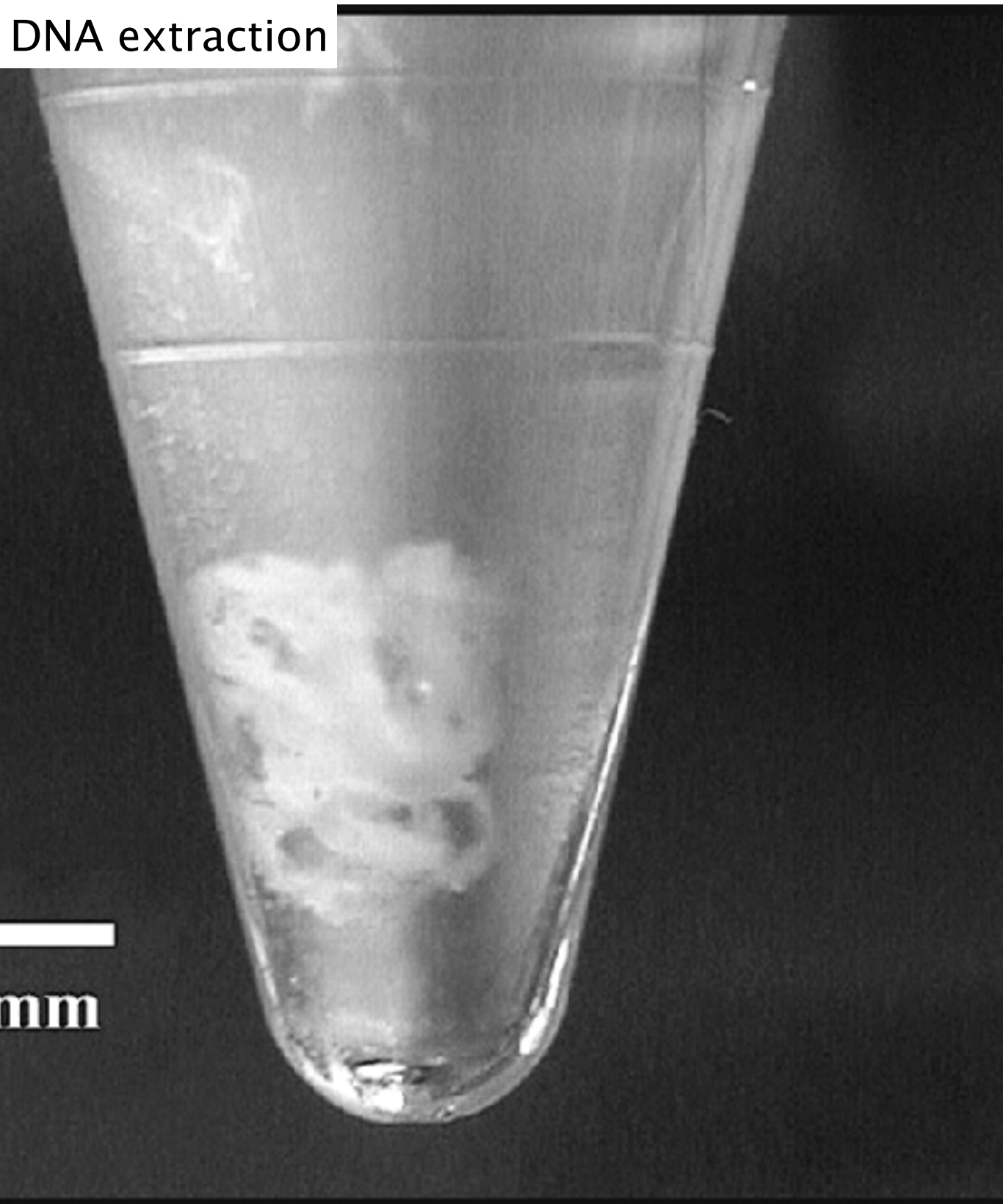
        }

        // groove under tube holders
        translate([0,0,0.8])
        difference() { // ring
```

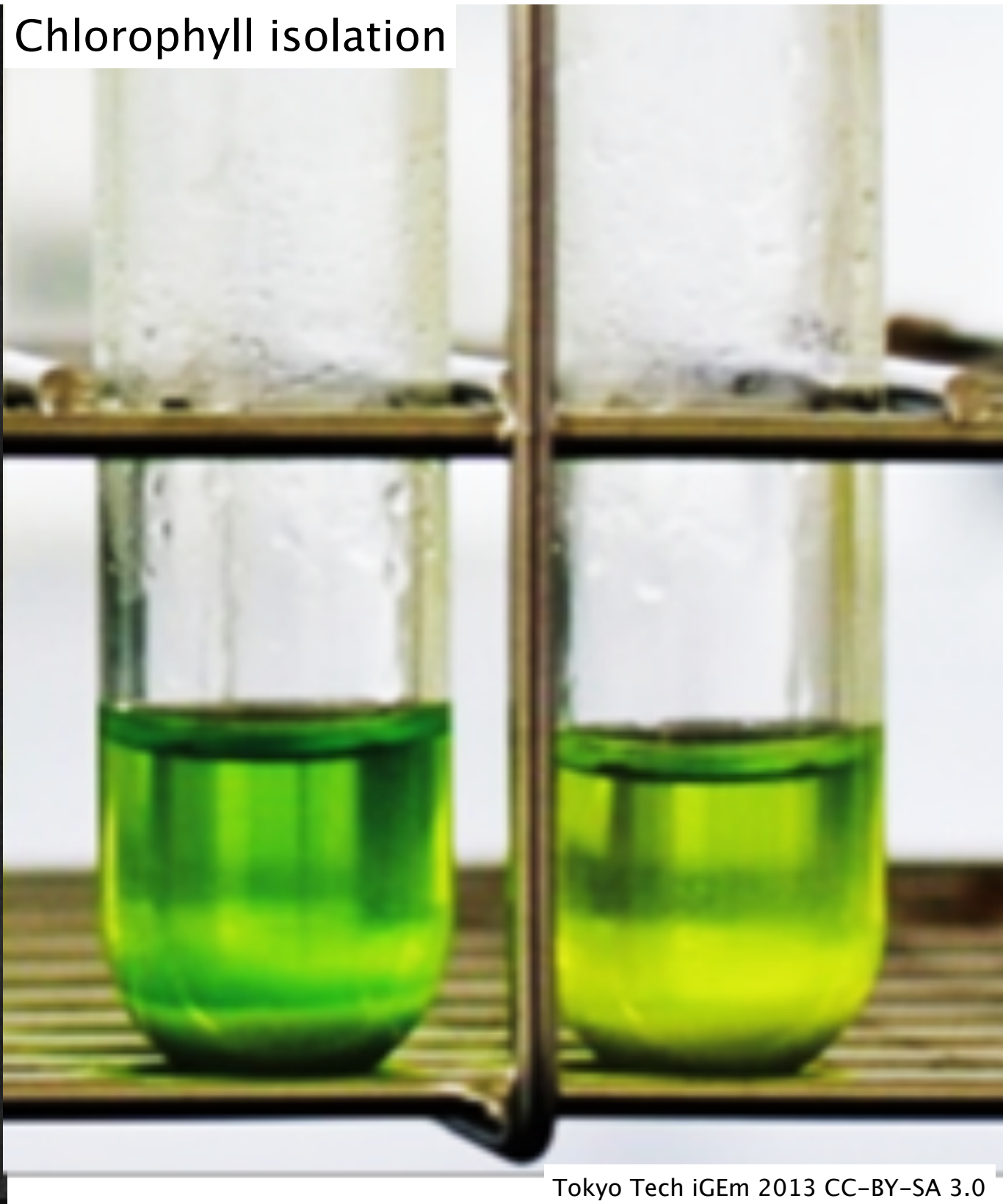


# Practicals

DNA extraction



Chlorophyll isolation







**some  
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reserved**